

Computer Vision Term Project

Projects	Roll No	Source
Camera Calibration and Fundamental Matrix Estimation with RANSAC	RSI2016504, RSI2017001, RSI2017002, IRM2013007	http://cs.brown.edu/courses/sci1430/
Scene Recognition with Bag of Words	PIS2016001, PIS2016002, PIS2016004, IRM2013009	http://cs.brown.edu/courses/sci1430/
Face Detection with a Sliding Window (viola jones)	IRO2016005, IRO2016007, IRO2016008, IRM2013013	http://cs.brown.edu/courses/sci1430/
CNN on CIFAR-10	PRO2016001, PRO2016002, IIS2016008, IRM2013010	Stanford
Structure from Motion	IIS2016001, IIS2016004, IIS2016006, IRM2013012	http://cs.brown.edu/courses/cs143/2011/proj5/
3D reconstruction from disparity	IHC2016010, IHC2016009, IHC2016008, IRM2013015	
Segmentation of objects in natural images.	IHC2016006 IHC2016003 IHC2016005 IHC2016006	
3D Reconstruction from Dynamic Scenes	IRM2013016 IRM2013017 IRM2013018 ISM2013013	